# Application Scenario

**How Equipment Connectivity Works in the Factory** 

### **Pain Points of Global Manufacturers**

# **Less Usability from Past Projects**

Complex automation projects always require long development times and efficiency is highly related to profit. At the same time, end users have to maintain several individual PLC or HMI development tools for applications instead of a single integrated interface. And because traditional development tools do not allow similar application parts to be inherited as modules from former projects, costs can quickly spiral.

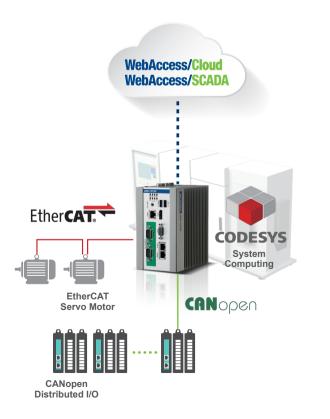


### **Legacy Devices and New Expansion**

It is difficult for manufacturers to replace legacy fieldbus devices which perform solidly but are limited by Ethernet-based upgrades, which need time to integrate properly. However, during transition they also suffer from compliance between legacy devices and new add-ons since the system contains a mix of fieldbus protocols.

### **Infeasible for Analysis**

Advanced data analysis is always done by IT systems with powerful computing capabilities. Nevertheless, open communications such as Modbus/ OPC are required for bridging devices at the OT level and system analysis at the IT level.





# **Ordering Configuration Table**

# SRP-FEC210 Programmable Real-time Machine Control

# **Package Offering**

# **Application Software**

CODESYS V3.5 SoftMotion & Visualization (Target & Web) x1

Preinstalled CODESYS V3.5 SoftMotion & Visualization (Target & Web) Runtime

System Computing : UNO-1372G-E3AE x1

Intel<sup>®</sup> Atom™ DIN-rail Automation Computer, 128G SSD, MRAM, CANoper OS:
Microsoft® Windows
Embedded 7 Pro x1
Preinstalled Microsoft® Windows

## **Optional Configuration**

	Option 300 I/O & Peripherals	
Qty:	[301] EtherCAT Distributed Digital I/O (AMAX-4830-AE) [302] EtherCAT Distributed Digital Output (AMAX-4834-AE)	□ Qty:
	Option 400 Add-on Accessories	
Qty:	[401] Power Adaptor (PWR-247-CE)	Qty:
	Qty:	Qty: [301] EtherCAT Distributed Digital I/O

# Order in 3 Easy Steps



**ADVANTECH** 

Enabling an Intelligent Planet





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# **iFactory**

Solution

Platform

# **Equipment Connectivity Solution**

**Easy Programing for Real-time Machine Control** 

Ready SRP-FEC210



**CODESYS** 



Real-time Data Acquisition & Visualization

**Shorten Development Time** 

**Real-time Soft Motion Control** 







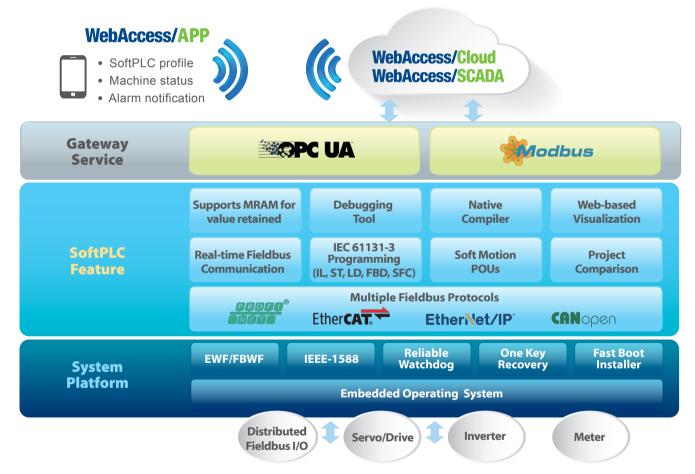


# **Entering a New Era of Smart Manufacturing**

# Introducing SRP-FEC210 Solution for Programmable Real-time Machine Control

This Solution Ready Platform allows users to reduce development time by supporting object-oriented programming (OOP) that is fully compliant with IEC 61131-3 standard and Program Organization Units (POU) inheritance from similar applications. The HMI is applied to the same IEC 61131-3 development environment. SRP-FEC210 guarantees real-time dual fieldbus data acquisition of PROFINET, EtherCAT, EtherNet/IP and CANopen communications. Users can collect data from Ethernet fieldbus and CANopen simultaneously Moreover, it achieves real-time EtherCAT soft motion control for single or multi-axis movements of electronic CAMs/ gears on CiA DSP 402 controllers and virtual axes by certified PLCopen motion POUs.

# Software Architecture and Key Design Features



# SoftPLC Design Feature



### IEC 61131-3 Programming

- 1. IL (Instruction List)

- 3. LD (Ladder Programming)
- 4. FBD (Function Chart Programming)
- 5. SFC (Sequential Function Chart)



# **CODESYS Soft Motion Module**

- 1. Single-Axis Function Block • MOVE ABSOLUTE • MOVE RELATIVE
- HOME STOP POWER . Multi-Axis Function Block
- CAMIN CAMOUT GEARIN GEAROUT



# **Visualization**

- . Controller/ Input Options
- 2. Table/ Chart
- 3. Graphical /Animation Options
- 4. Support WebVisualization for remote



# Compliant to 3rd party Fieldbus Device

Supports GSD/ EDS/ XML file

# System Block Diagram

# WebAccess/APP



- SoftPLC profile
- Machine status
- Alarm notification







- Open interface for cloud dashboard monitoring & big data analysis
- Precaution alarm for equipment preventive maintenance
- Monitor all fieldbus-connected motion device states



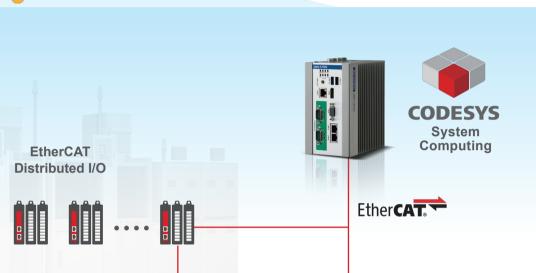
**EtherCAT Servo Motor** 







**Real-time Dual Fieldbus Communication** 

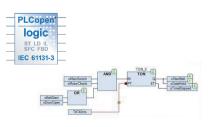


Real-time EtherCAT Motion Control

# Key Advantages/ Features

## **Shorten Development Times** IEC 61131-3 Compliant

Supports real object-oriented programming fully compliant with the IEC 61131-3 standard to inherit existing POUs to reduce development time and errors.



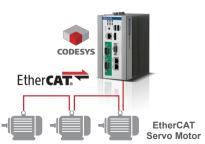
### Real-time Dual Fieldbus Data Acquisition

Supports real-time fieldbus protocols. Users can collect data from more than one Ethernet fieldbus and CANopen port simultaneously.



### Real-time EtherCAT Soft **Motion Control**

Supports CODESYS certified PLCopen motion POUs for single or multi-axis movements of electronic CAMs/ gears on CiA DSP 402 controllers and virtual axes etc



# Solution-Ready-Platform Package

### **CODESYS Runtime Software**

Preinstalled CODESYS SoftMotion & Visualization (Target & Web) Runtime



### **UNO-1372G-E3AE**

Intel® Atom™ Quad-Core DIN-Rail PC, 4GB RAM, 128G SSD, MRAM, CANopen, Microsoft® Windows Embedded 7 Pro.



### **CODESYS Fieldbus Library**

Integrated Fieldbus Support in the IEC 61131-3 Tool, from CANopen to real-time Ethernet, including the Protocol Stacks.









